

Algorithms R&D: Updates

Jan. 15th, 2020



S. Bhatnagar
Algorithms R&D Group



Algorithms R&D Group (ARDG)

- Rational
 - Longer term focus for algorithms R&D
 - Recognize R&D as a distinct step in software development cycle
 - Identify algorithms R&D work necessary to full-fill long term NRAO goals
 - Formalize the way AR&D is done at NRAO
 - Work on unforeseen issues that require AR&D (e.g. VLASS imaging)
- Under DMSP: ARDG Lead reports to Head of DMSP
- Develop a road map in collaboration with DMS, SSR, EVLA, ALMA, SCG, Sc. Staff reps. Update ~yearly.
- Disperse information about its activities



Algorithms R&D Group (ARDG)

- Current membership
 - S. Bhatnagar (Scientist), Group Lead (0.75 FTE)
 - P. Jagannathan (Assistant Scientist) (0.75 FTE)
 - M. Pokorny (Software Engineer-IV, 2-year term position for ngVLA) (1 FTE)
 - B. Kirk (PhD student)
 - Mingyu (Genie) Hsieh (Software Engineer-IV); New hire (starting Feb. 03,2020) (1FTE)
 - Srikrishna Sekhar, Joint NRAO-IDIA/SA PDF; New hire (starting Feb. 2020)
- Total effort:
 - 2.5 FTE from 3 full-time staff members
 - 1 FTE from one 2-year term position
 - 1 PDF + 1 student



Algorithms R&D Group (ARDG)

- Primary deliverables
 - Scientific publications demonstrating the working of the algorithm/technique
 - Technical description, limitations, limits of applicability, etc.
 - A software prototype implementation, regression with test data and reference products
 - Software interface description
 - Assistance in integration with production software, commissioning, (re-)training support staff
- CASA code base as the development platform (by choice)
 - Minimize development overheads in the R&D stage
 - Minimize cost of integration with the production package



ARDG Road Map

- Items broadly categorized as
 - Planned for delivery
 - » Proof-of-concept demonstrated
 - » Usually in the stage of prototype implementation
 - In active R&D stage
 - » R&D in progress
 - » First goal usually is a PoC demo
 - Potential R&D topics
 - » Exploratory projects
 - » Often parts of PhD or Masters level projects
 - Consulting/Maintenance
 - » Support staff, CASA staff, others...
 - » Maintenance support for algorithmic issues once in production



ARDG Road Map 2019

- Joint SD-Interferometric imaging
- Scientific commissioning of AW-Projection
- Wide-field full-pol. Imaging (ALMA Study Project)
- Full-Stokes imaging
- Asp-Clean (port from AIPS++!) + new ideas
- ngVLA
 - Size of computing
 - Algorithms
- ML/AI Application to RA (B. Kirk's PhD)
 - As a start, detect and classify artifacts in images from pipelines



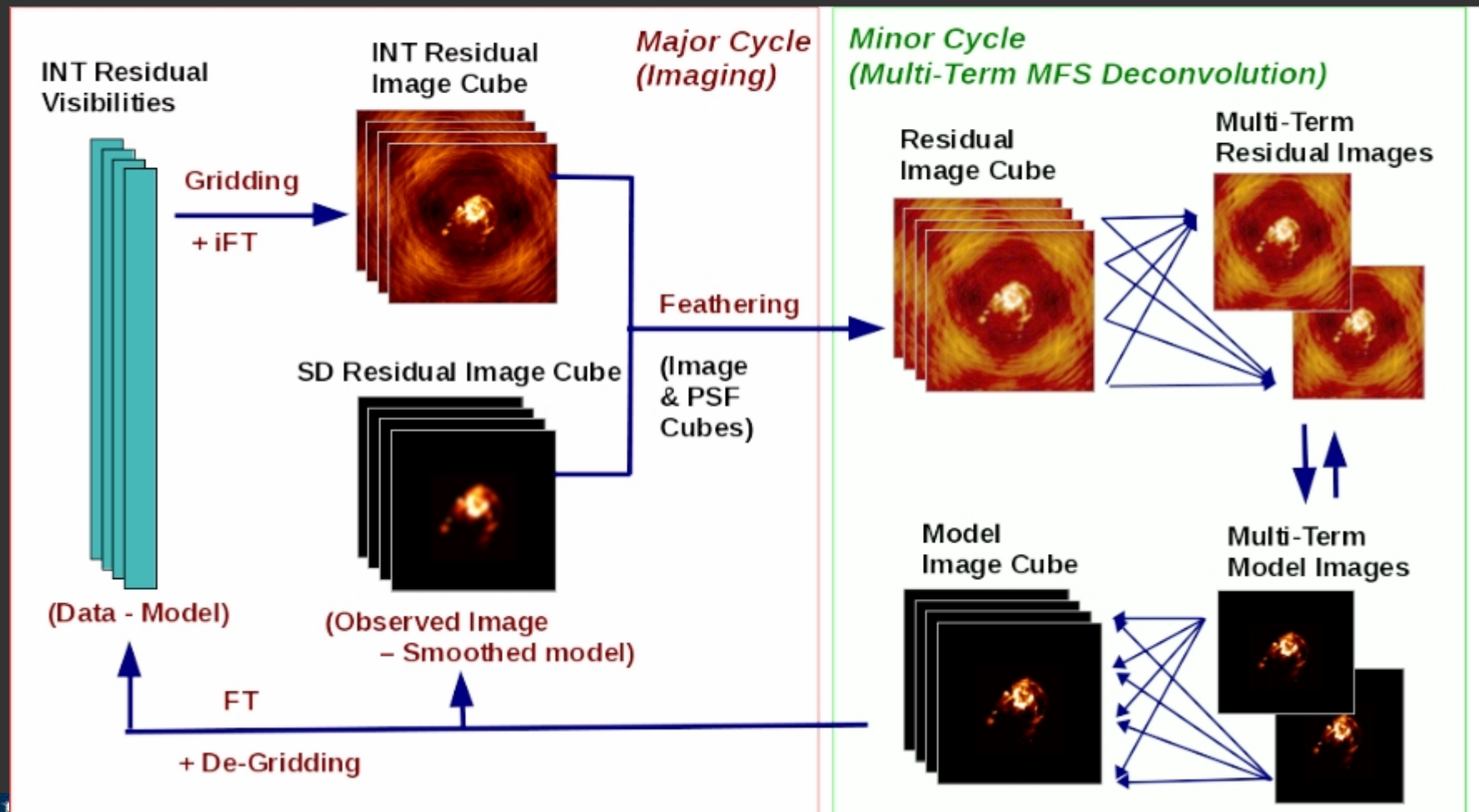
What we actually ended up doing?

- Joint SD-Interferometric imaging [Done]
- Scientific commissioning of AW-Projection [Done]
- Work on VLASS imaging (a report now exist) [Done]
 - Deep-dive into imaging problems
 - PB models, Pointing corrections, HPC
- Follow-up VLASS work [Done]
 - CFCache Lazy Fill
 - Corrections for antenna pointing offsets
- Size-of-computing estimates for the ngVLA [Done/In progress]
- Wide-field full-pol. Imaging (ALMA Study Project) [Done/In progress]
 - New holography data, A-term models

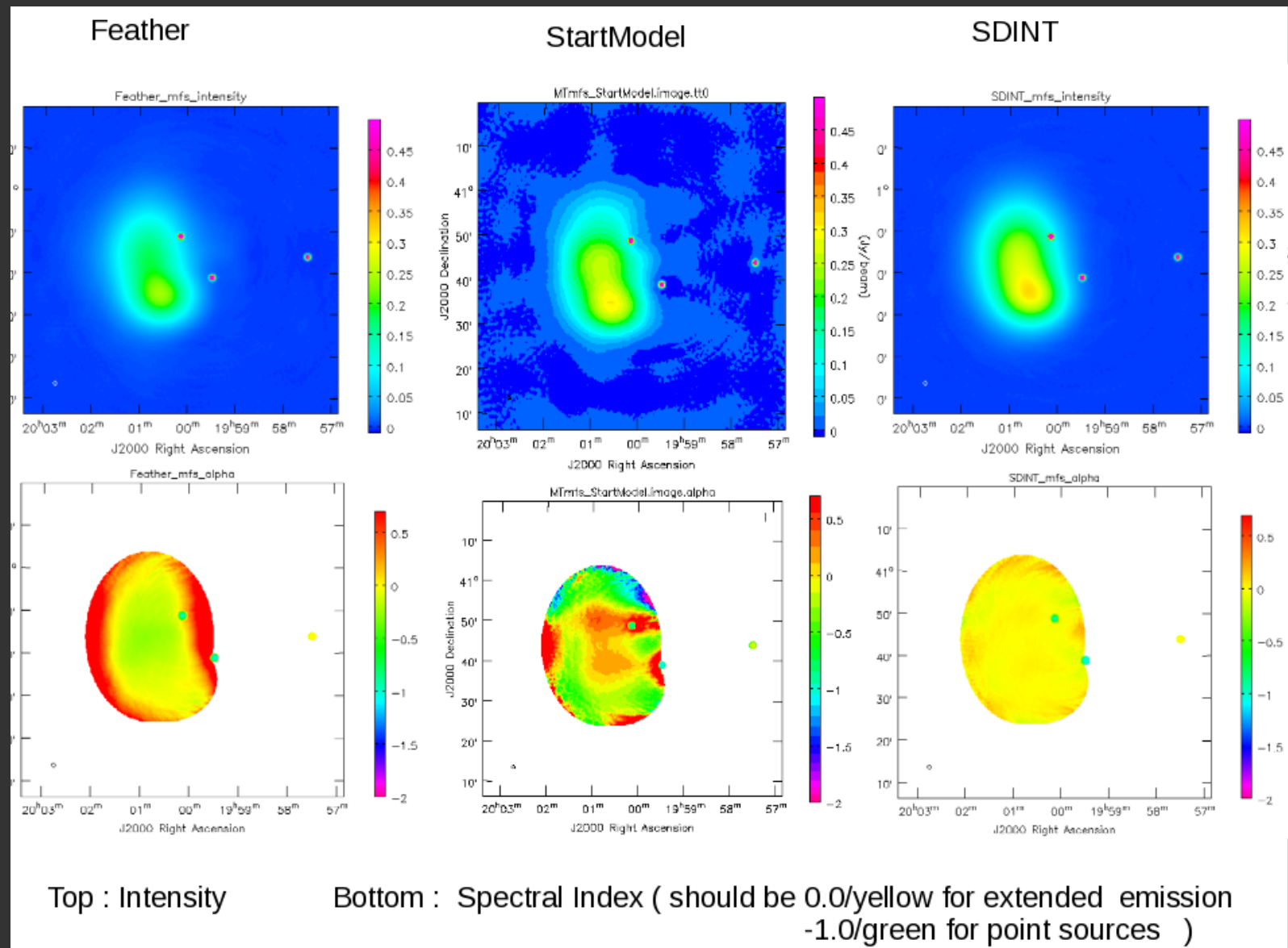


SD-Int joint reconstruction

Examples for SD+INT joint reconstruction.



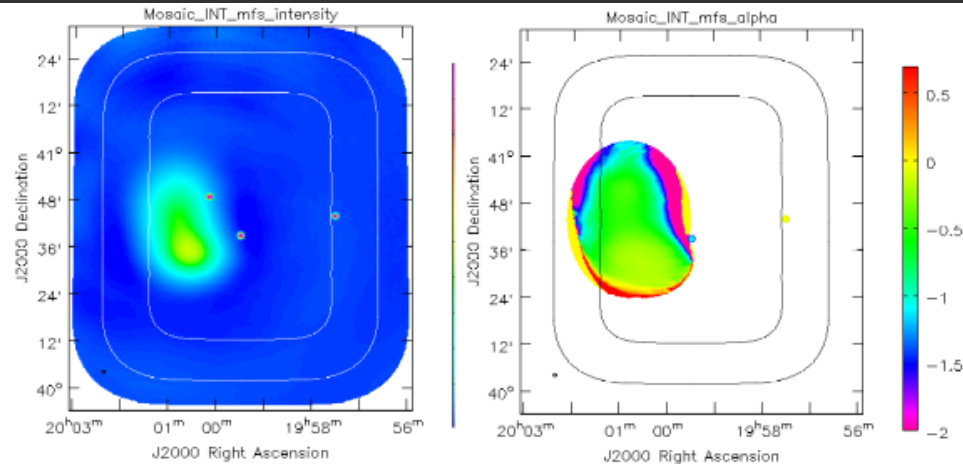
SD-Int Joint reconstruction



SD-Int joint reconstruction

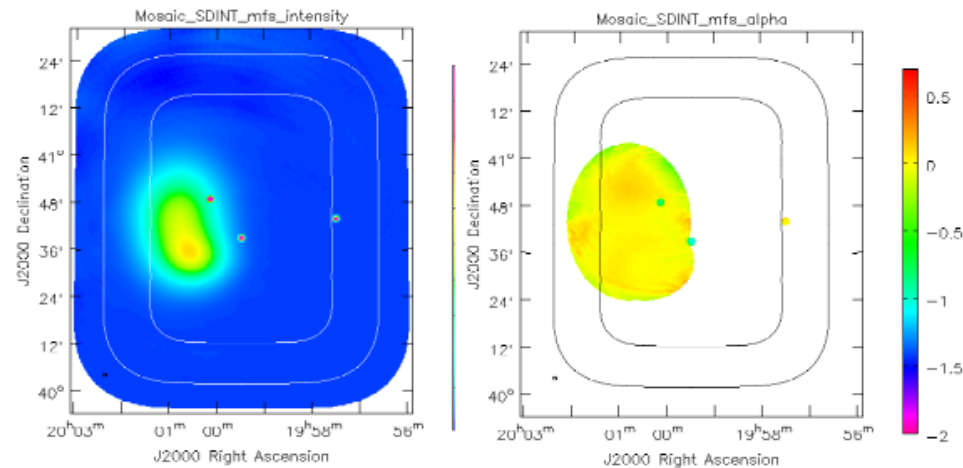
Wideband
Mosaic

INT only



Wideband
Mosaic

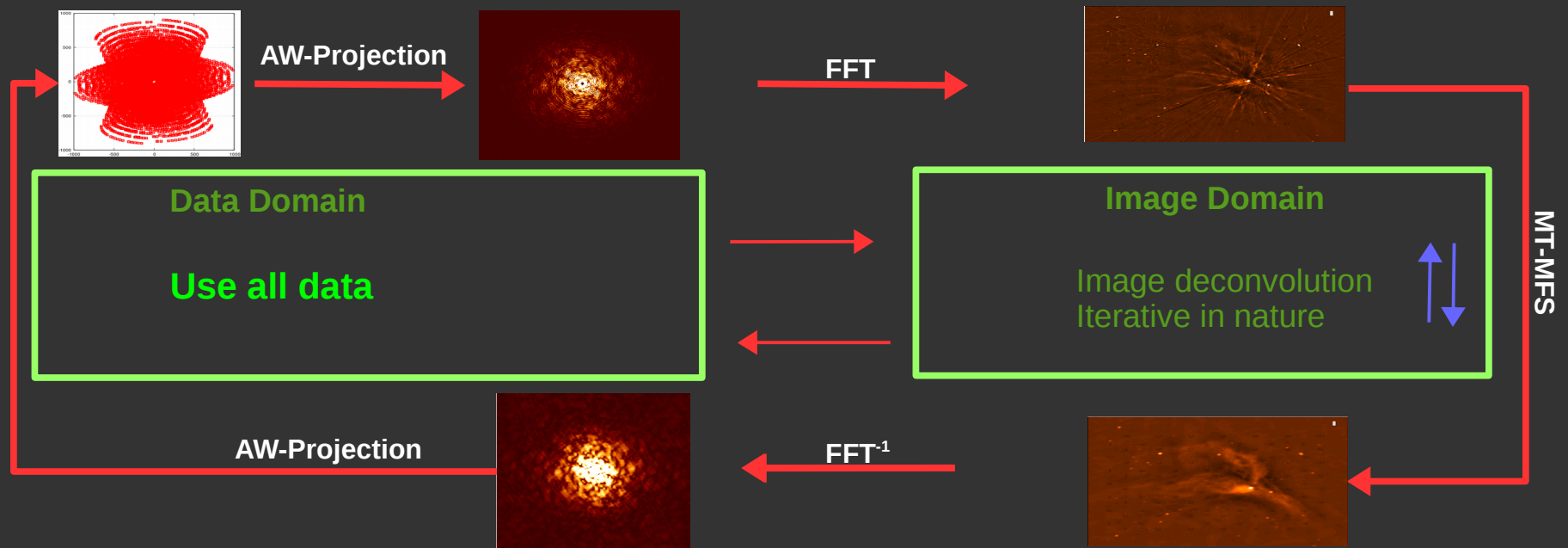
SDINT



Wideband Mosaic : gridded='mosaic' with specmode='cube' and deconvolver='mtmfs' with specmode='mfs' with conjbeams=T implemented as part of the SD+INT merging process (in python). [[Used PySynthesisImager prototyping interface]]

WB AW-Projection Commissioning

- Joint WB AW-Projection + MT-MFS for wide-band wide-field continuum imaging



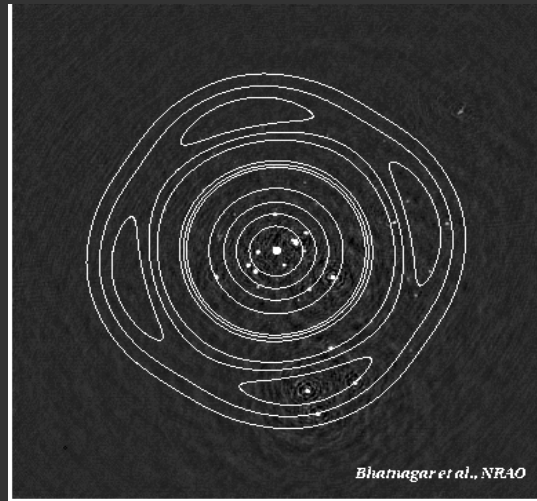
WB AW-Projection:
Make image free of PB- W-term effects

MT-MFS:
Images corrected for instrumental effects
Reconstruct WB sky model

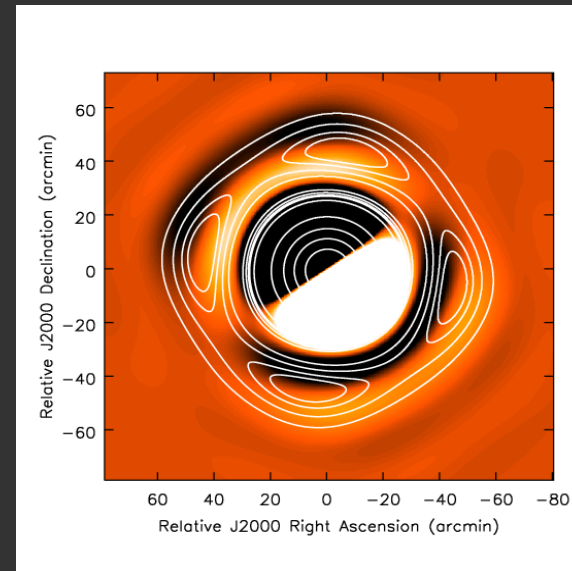


Project-out PB effects before transforming to the image domain
Image domain algorithms then need to model only the (WB) sky emission

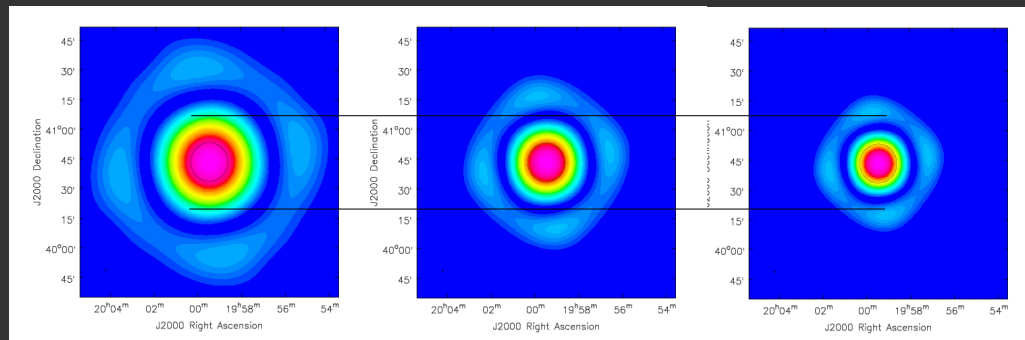
WB AW-Projection Commissioning



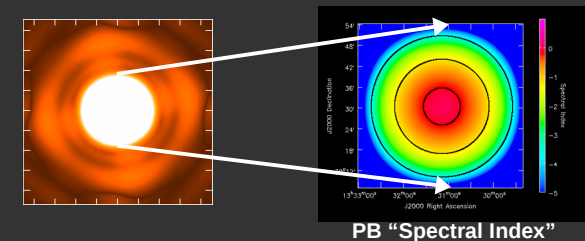
Time dependence



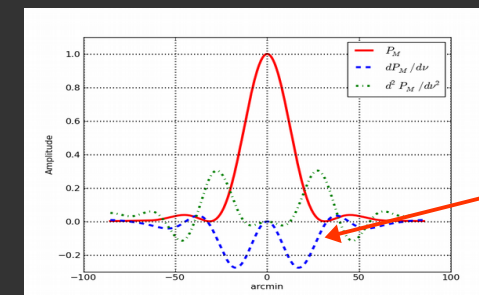
Polarization dependence



Frequency dependence

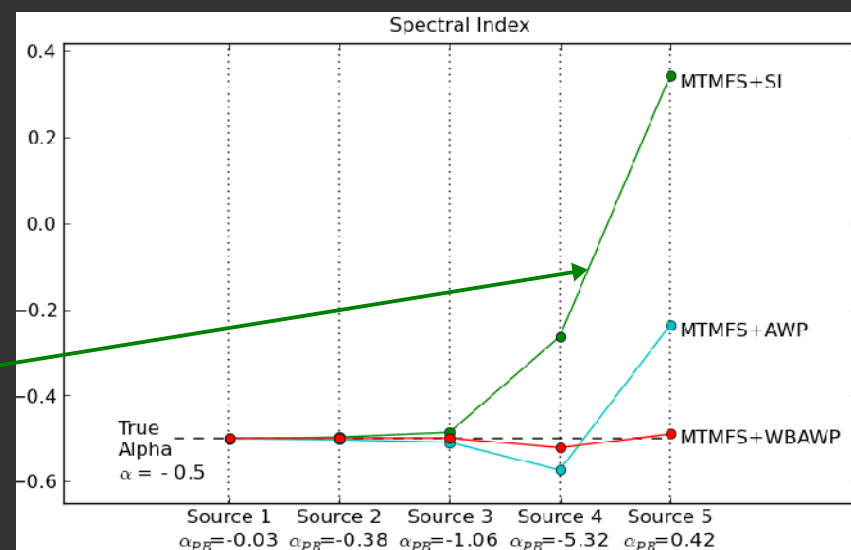
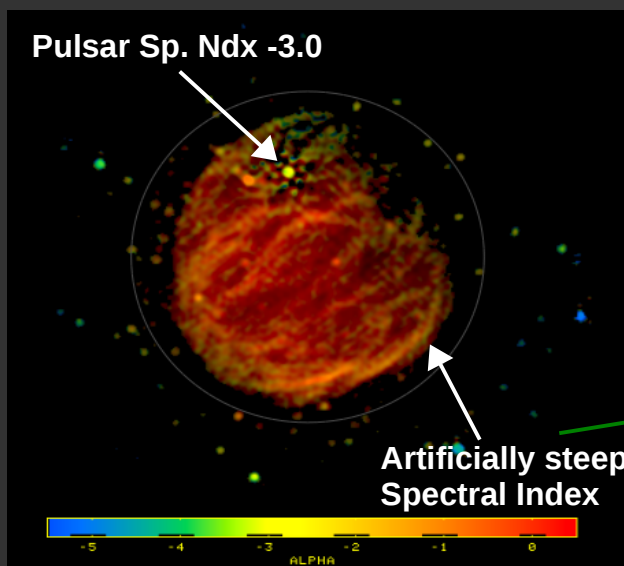
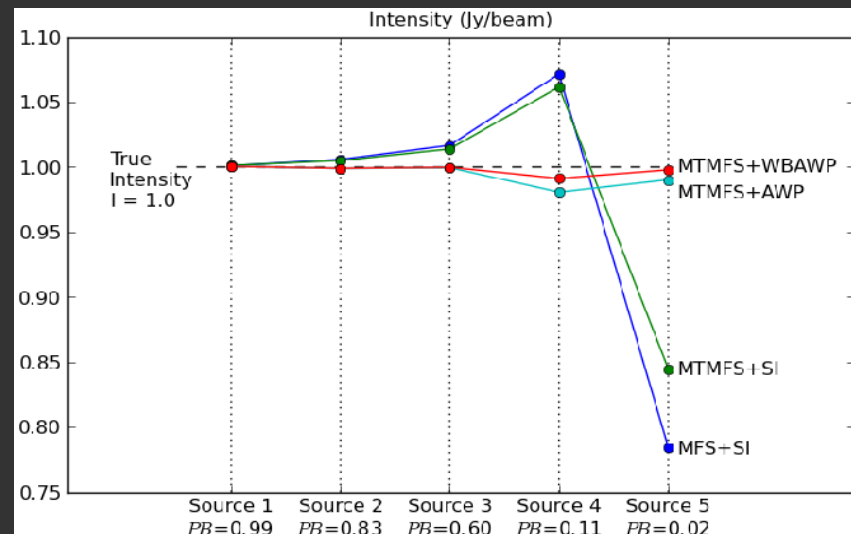
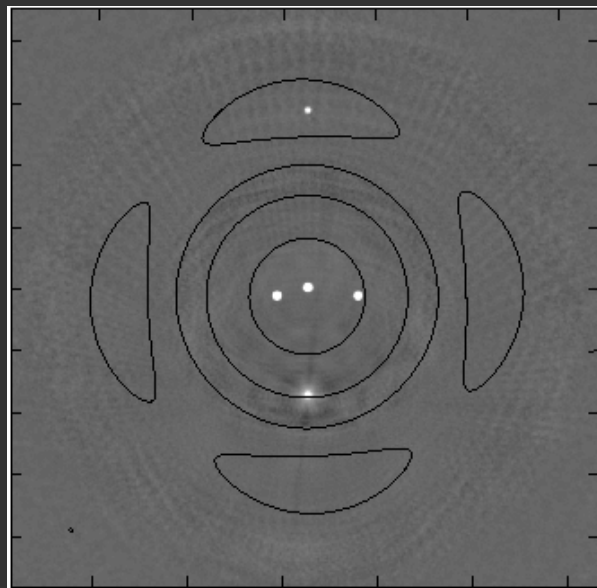


PB "Spectral Index"



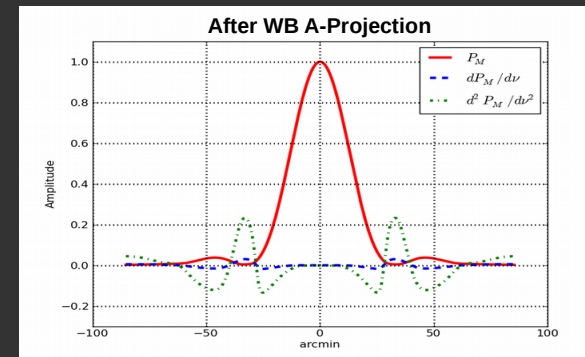
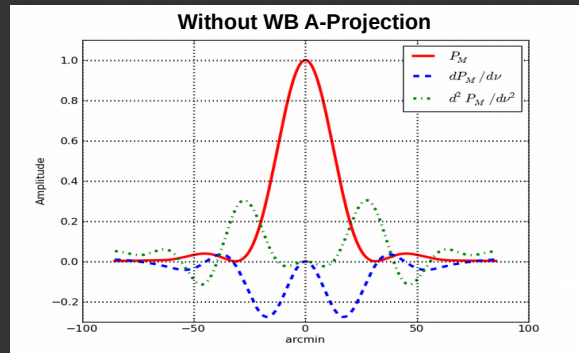
PB Frequency dependence (blue curve)

WB AW-Projection Commissioning

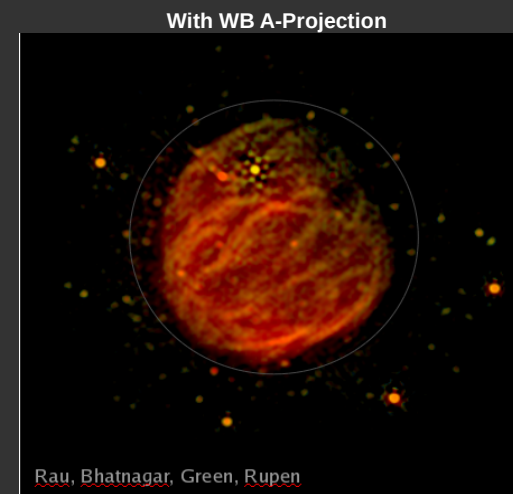
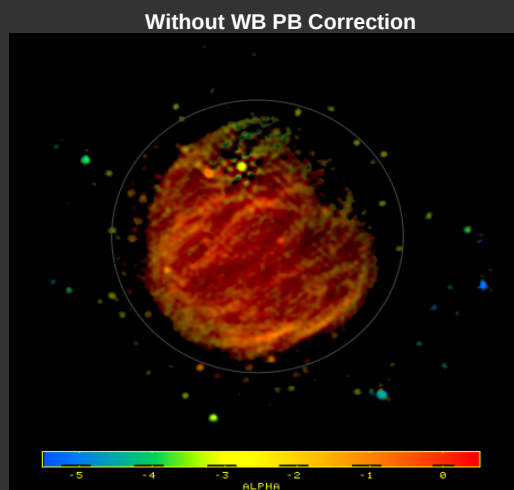


WB AW-Projection Commissioning

- WB A-Projection + MT-MFS
 - WB A-Projection for PB

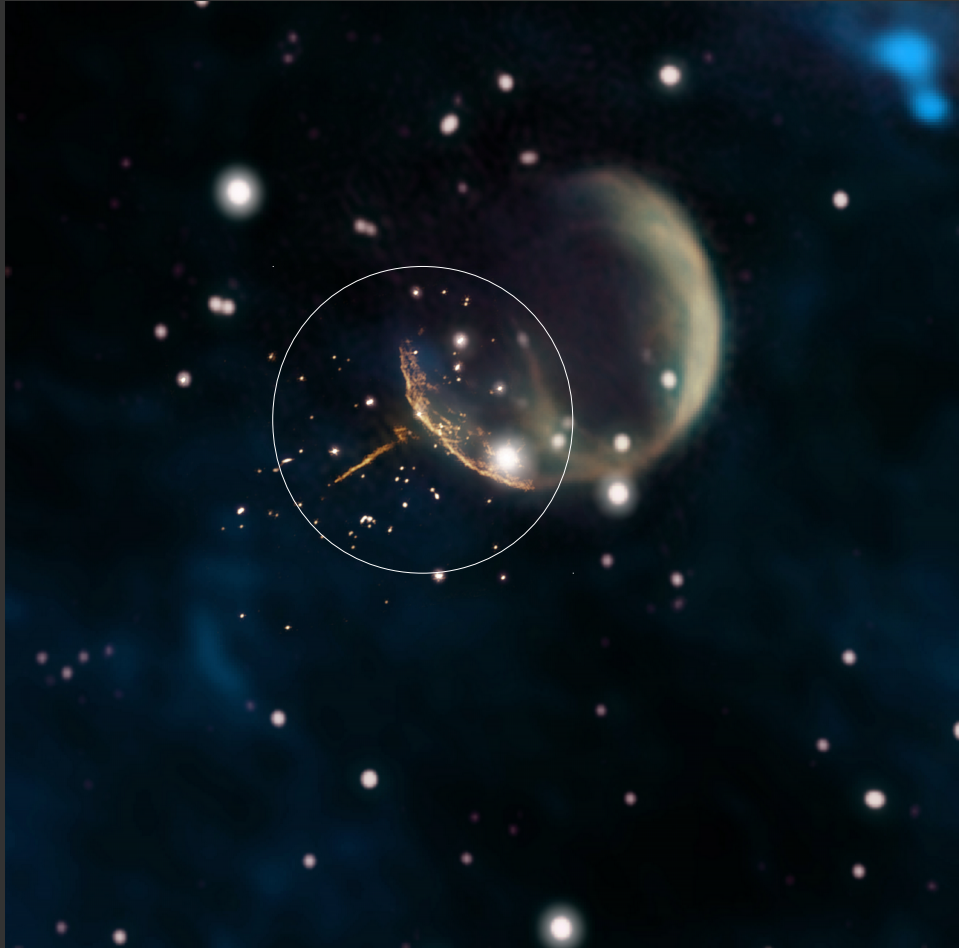


- MT-MFS for sky
- **Without PB correction the reconstructed spectral index increases with distance from the center**

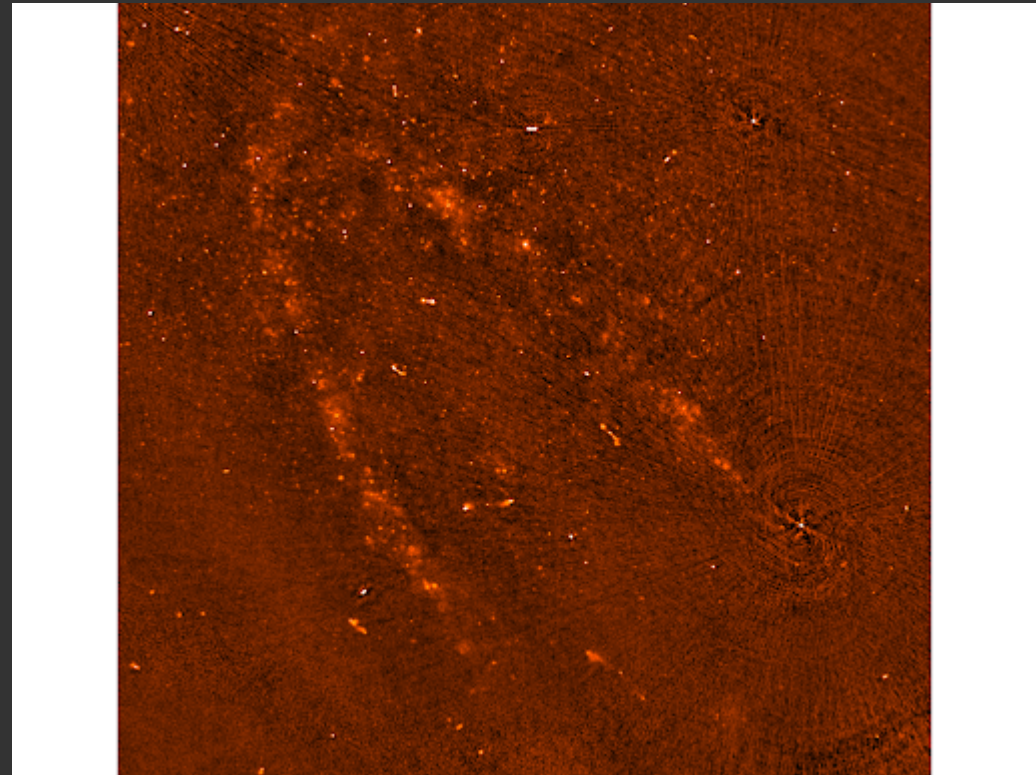


Wide-band Wide-field Imaging

- Wide-band full-beam imaging at L-Band



L-Band, B,C-array mosaic: 512 W-Planes + WB PB rotation
7 $\mu\text{Jy/B}$, 11 $\mu\text{Jy/B}$ near strong source (6% PB): DR ~500,000
11 cores x 4 nodes, ~1 TB data: 4 days / major cycle

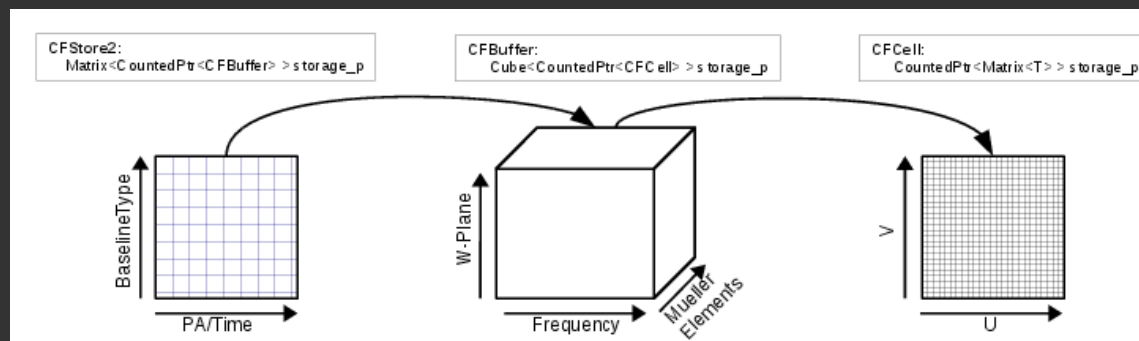


Wide-band Wide-field Imaging

- Generalized CF: $CF = PTerm * ATerm * Wterm$
 - Can be configured for Std, W-, A-, AW-Projection
 - Mosaicking, correction for pointing offset
 - Full pol, WB corrections

Operation	aterm	psterm	wprojplanes	CF
AW-Projection	True	True False	>1	PS*A*W A*W
A-Projection	True	True False	1	PS*A A
W-Projection	False	True	>1	PS*W
Standard	False	True	1	PS

- On-disk CFCache; re-usable
 - Easily parallelized, or deployed on special h/w [32K CFs in O(1hr)]
 - Lazy Fill mode: CF Paging algorithm to control memory footprint
 - Usable for managing pointing offset correction, Hybrid-Mueller,...

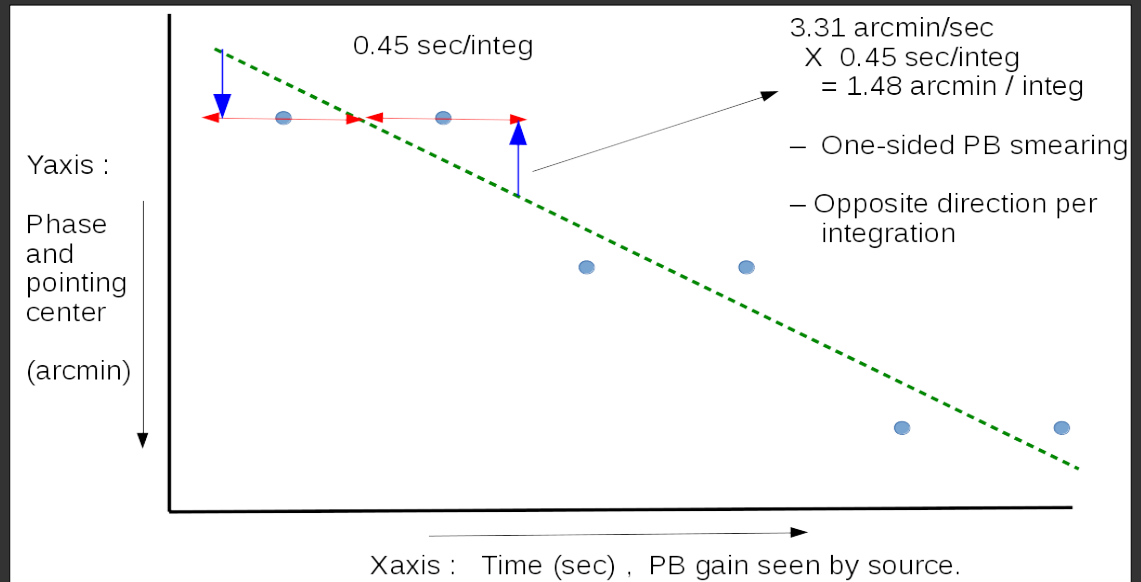
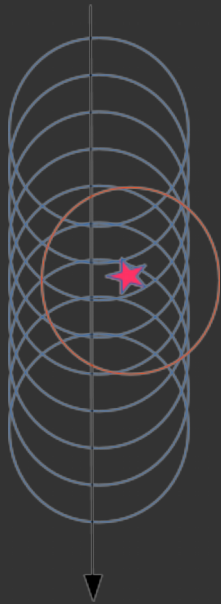


WB Mosaicking with the EVLA

- VLASS as an example of OTF
 - Continuum imaging in the 2 - 4 GHz band (fractional BW $\sim 67\%$)
 - Imaging 1×1 sq deg at a time using 40 pointings
 - OTF: Continuous antenna motion: 3.31 arcmin/sec, 0.45 sec integration per pointing
 - Correlator phase-center updates quantized in time
 - ~ 100 μ Jy/b noise limit
 - Resolution: ~ 2 arcsec
- Primary continuum scientific products
 - Source positions, flux, spectral indices, images
- Image size:
 - Wide-band sensitivity pattern about 2×2 sq deg.
 - 5400 pixels on a side (desired: 12K pixels on a side)
- Imaging
 - MT-MFS for image reconstruction
 - Algorithms for imaging still being evaluated



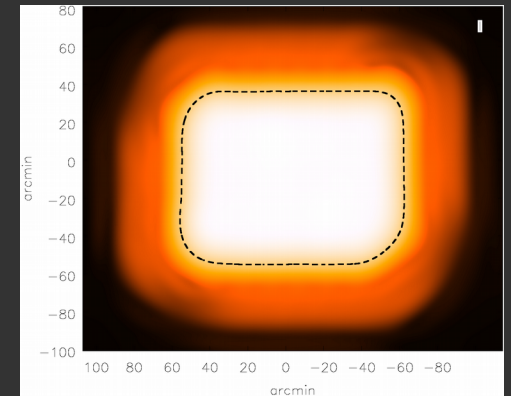
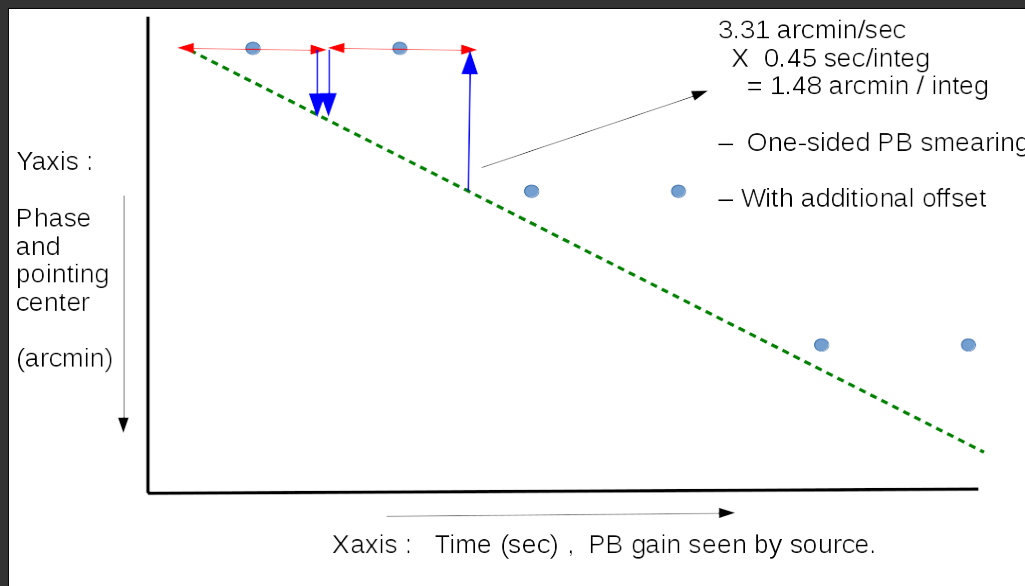
WB Mosaicking with the EVLA



- Error in fluxes, positions and spectral indices was too large
 - **No W-correction:** To reduce computing load, memory footprint
 - » Leads to position errors → flux and spectral index errors!
 - **Narrow-band A-Projection:** Minimize computing load and s/w complexity
 - » Ignore PB frequency dependence
 - **Ignore pointing offsets:** Was expected to “average out”
 - » Errors in flux and spectral index

WB Mosaicking with the EVLA

- Error in the reconstructed flux was dominated by errors in source positioning in the PB (pointing errors) and on the sky (W-term)
 - Pointing errors due to OTF mode + a software bug
 - Gain errors: PB sidelobe span $\sim 2\times$ antenna FoV

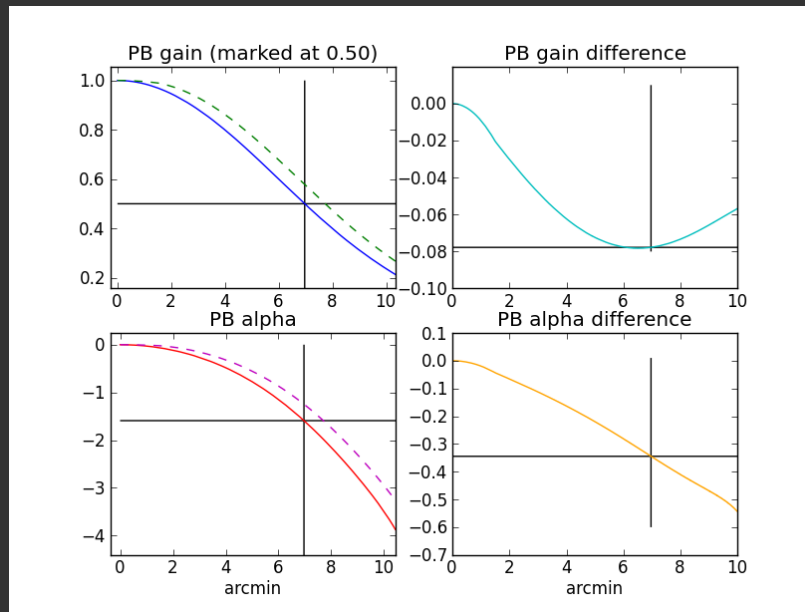


- Each pointing is a snapshot observation. W-term leads to radially-dependent source position offsets.
 - Actual position offset in a joint mosaic image is more complicated

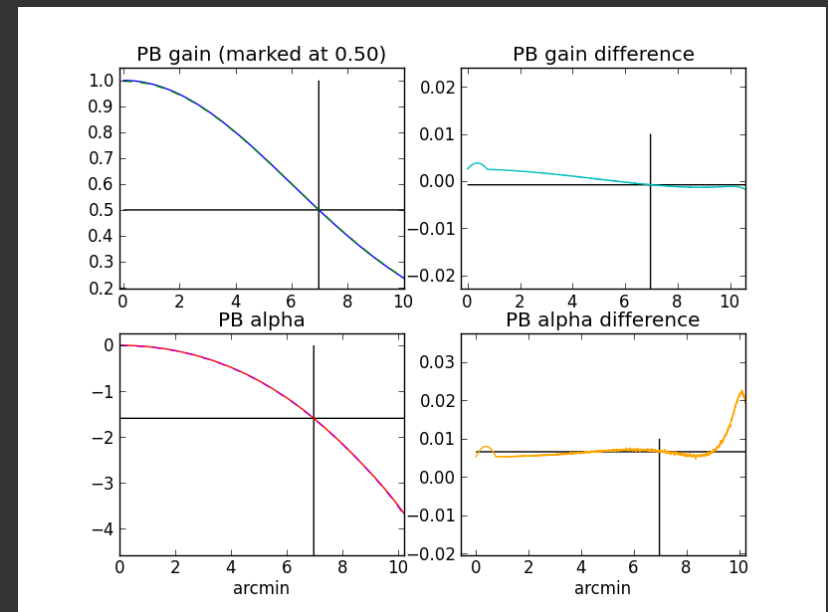
WB Mosaicking with the EVLA

- Effects of pointing errors and w-term do not in general “average out”
 - Source positioned in different parts of the PB of overlapping pointings
- Spectral index is extra sensitive to pointing and source position offsets
 - Systematic error of $>100\%$

Actual data



Intended data

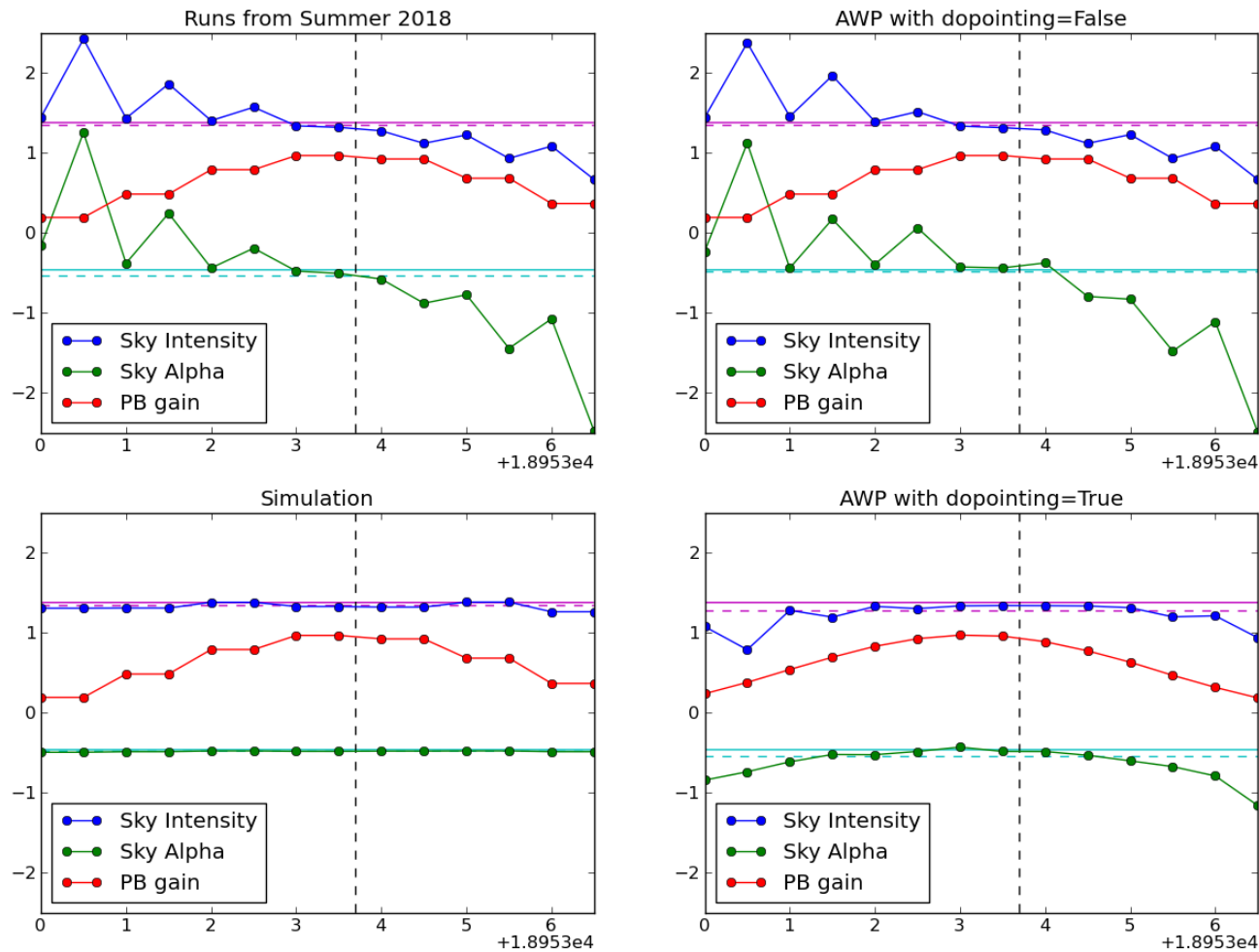


- Computing load *10-100x* larger



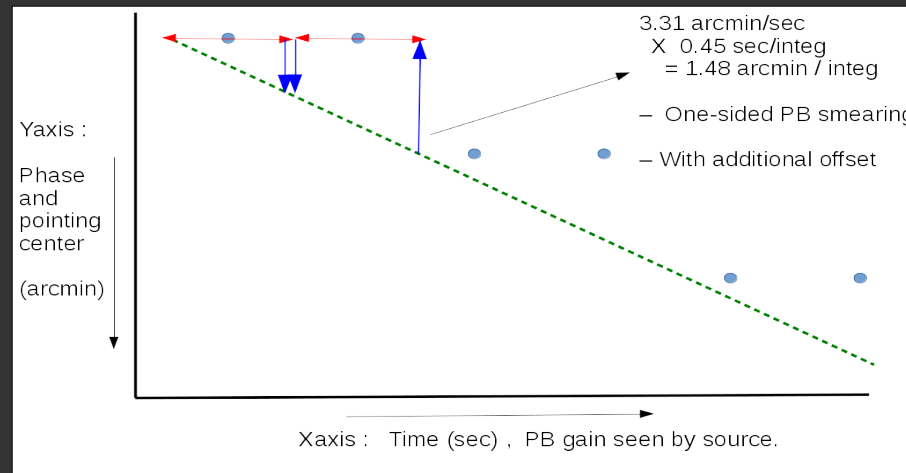
WB Mosaic imaging with EVLA

- WB AW-Projection with corrections for antenna pointing offsets



Correction for antenna pointing

- Proof of concept demo:
 - Imaged each integration in VLASS observation independently for a strong source (ARDG Memo)



- Homogeneous pointing correction
 - Apply same pointing correction for all antennas in the array

$$A_{ij} = A_{ij}^o \left[e^{(l_i - l_j)^2 \alpha^2 / 2} \right] \left[e^{i u (l_i + l_j)} \right]$$

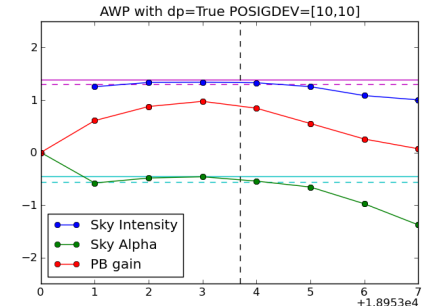
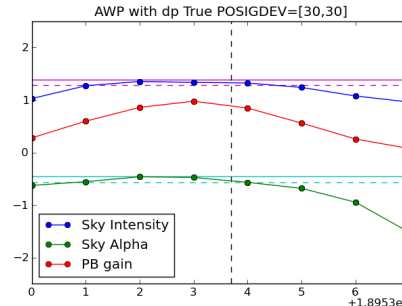
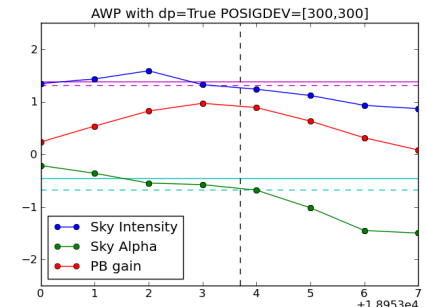
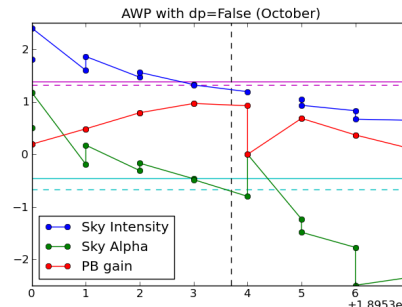
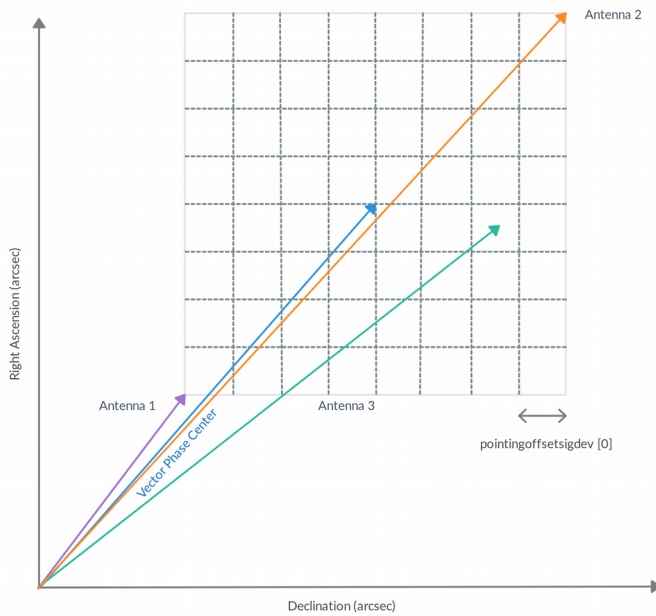
- Lower complexity, faster, but insufficient in general

Correction for antenna pointing

- Heterogeneous pointing correction; deeper implementation

$$A_{ij} = A_{ij}^o [e^{(l_i - l_j)^2 \alpha^2 / 2}] [e^{i u (l_i + l_j)}]$$

- Detect antenna groups with same pointing offset
 - » Needs to be computationally cheap
- Cache phase gradients for groups of baselines
 - » Can become a compute bottleneck [$N + N(N-1)/2$ scaling]
 - » Can become a memory footprint bottleneck for fully heterogeneous case

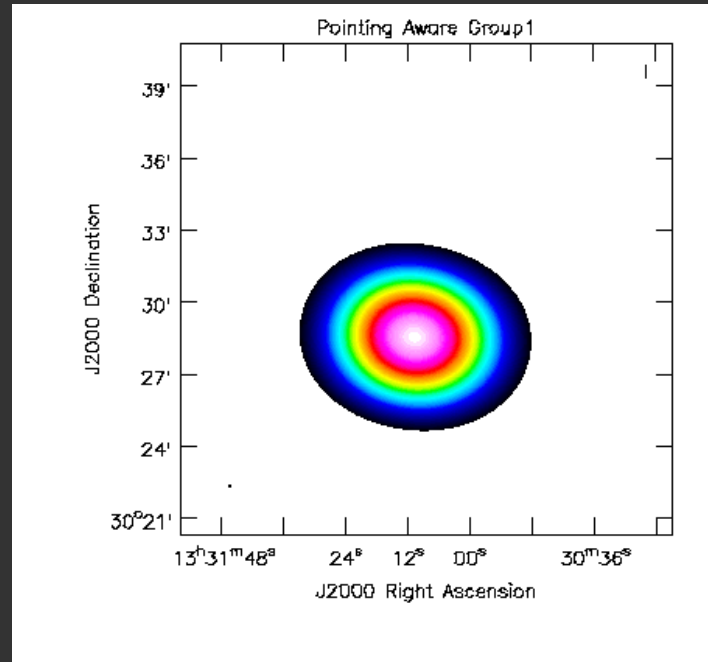


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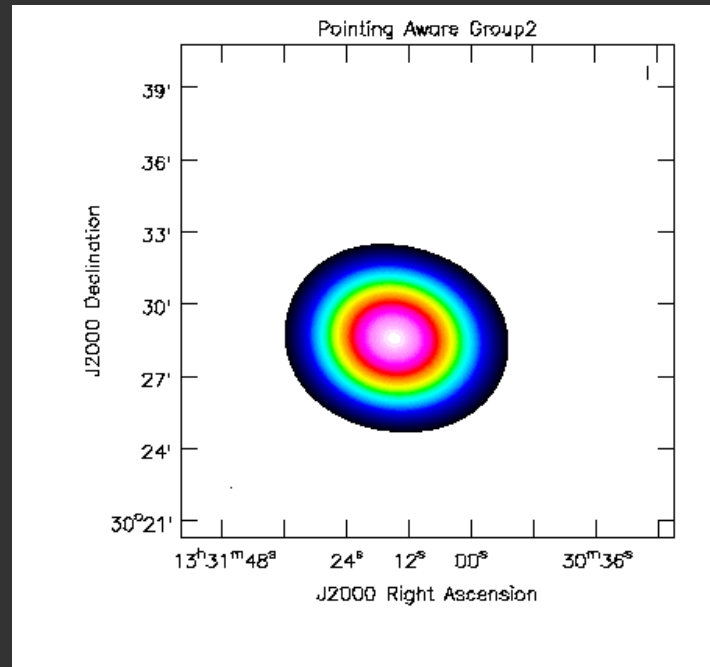


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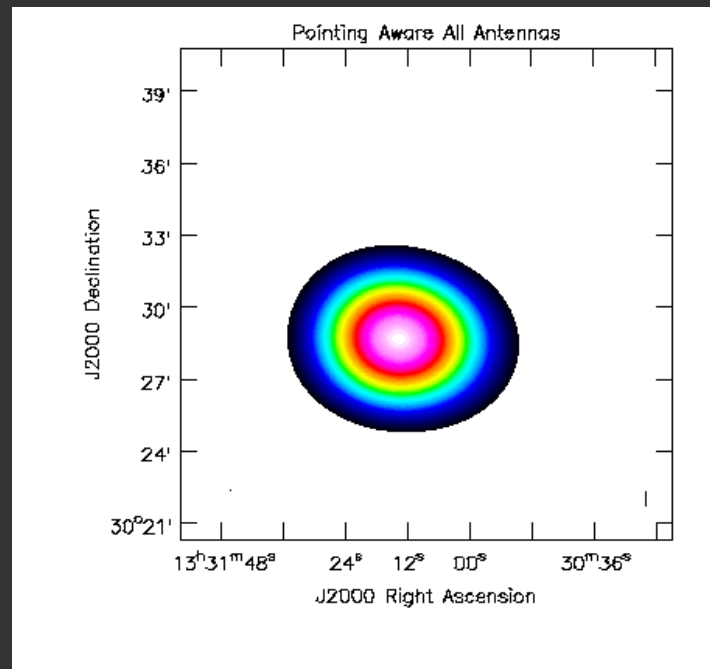


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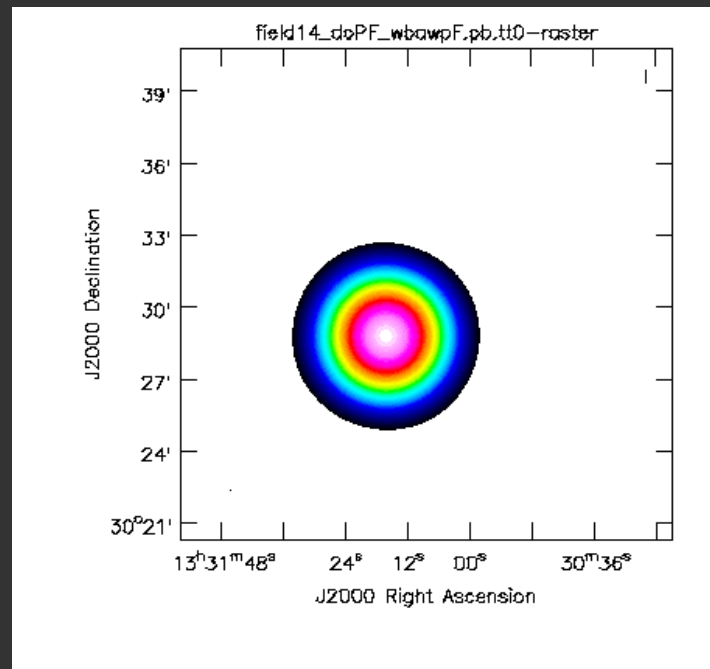


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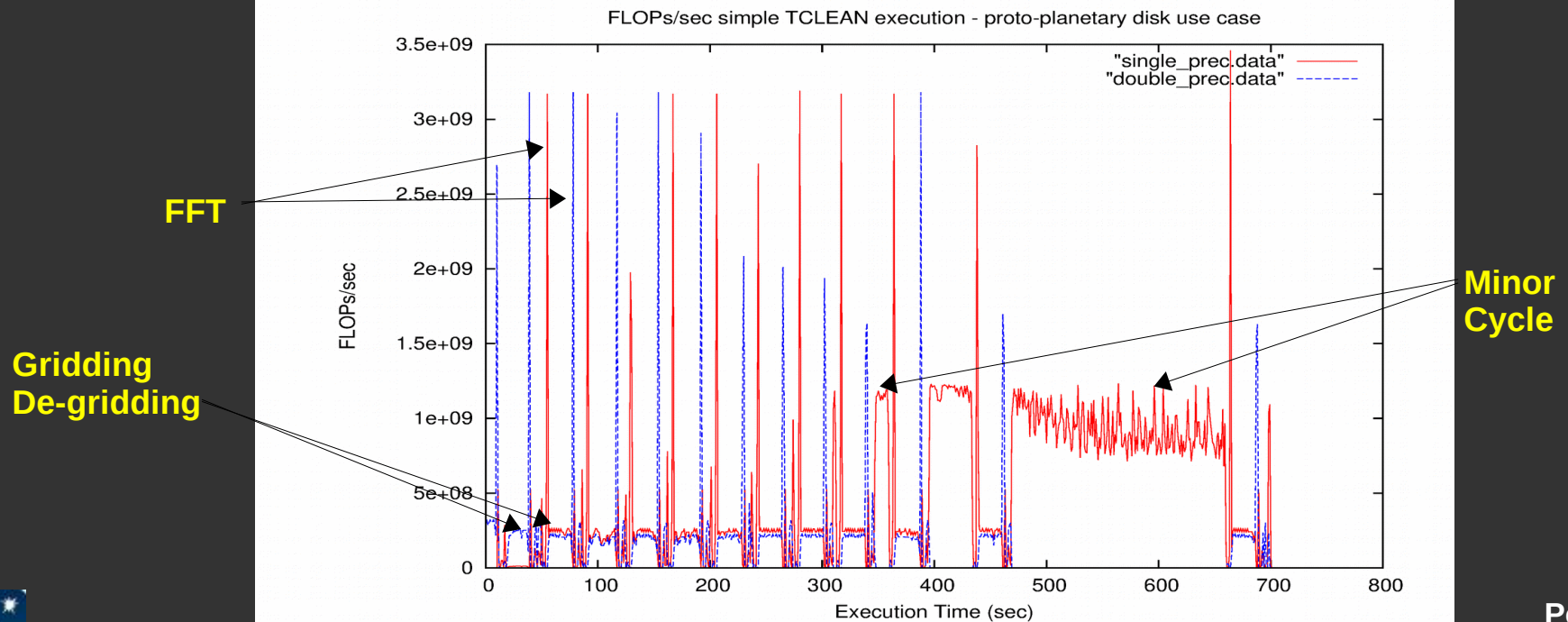
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Size-of-Computing for ngVLA

- Goals:
 - Make realistic estimate of SoC, assuming current algorithms and implementations are sufficient
 - Measure run-time performance in serial and parallel
 - Use scaling laws to predict required SoC for cost estimates

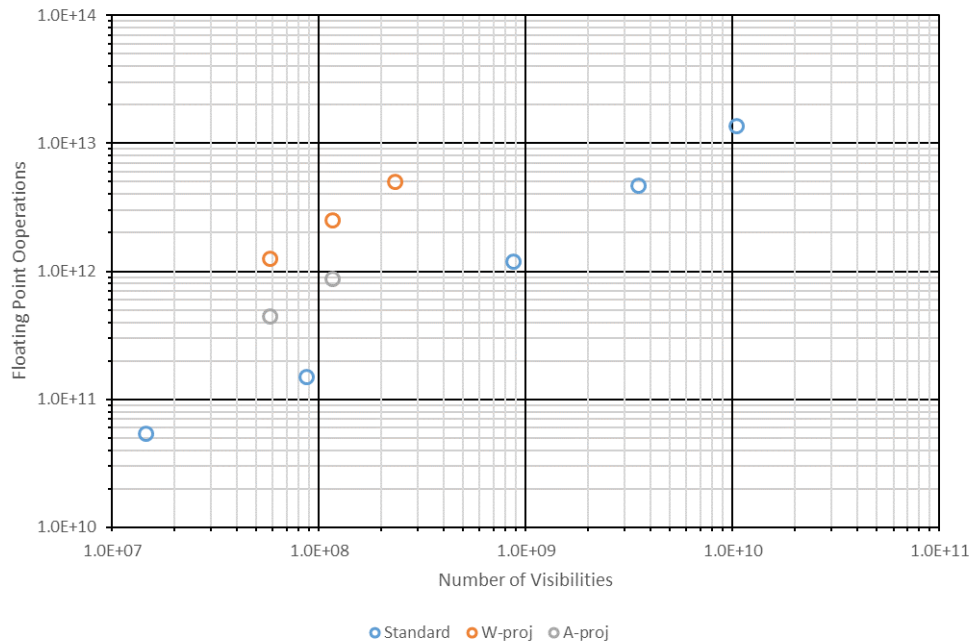


Pokorny
Hiriart
Bhatnagar

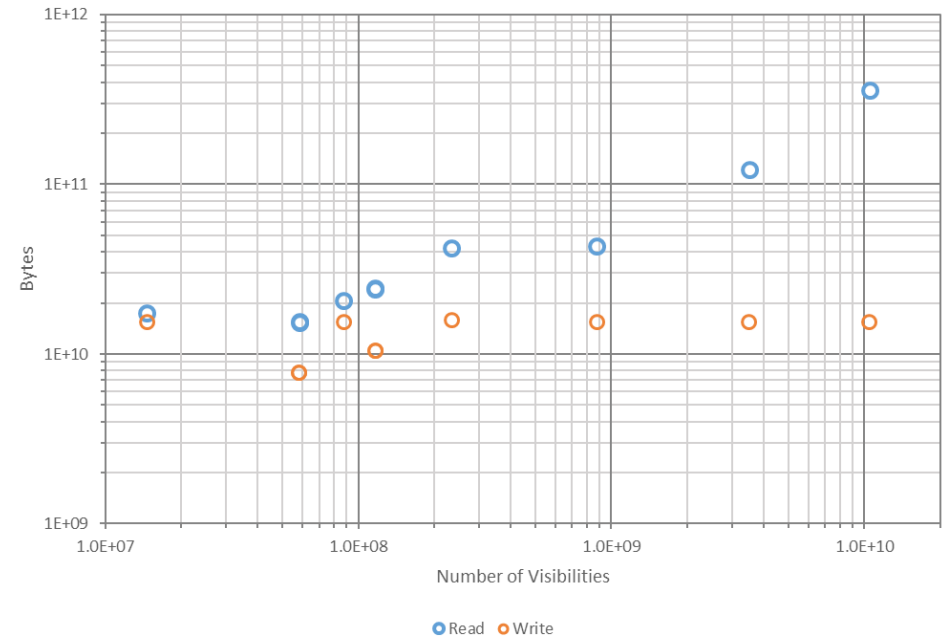
Size-of-Computing for ngVLA

- Identify a smaller set of Key Science Goals (KSG) that covers algorithms parameter space
- Instrument the imaging code for run-time measurements (Score-P)
 - Used a stand-alone application in C++ to directly use CASA C++ libraries

FLOPs per Gridding Cycle



IO per Gridding Cycle



Arithmetic Intensity (FLOPS/byte):
Std: 40 A-Proj.: 233 W-Proj.: 670

Projected SoC for ngVLA: ~60 PFLOPS



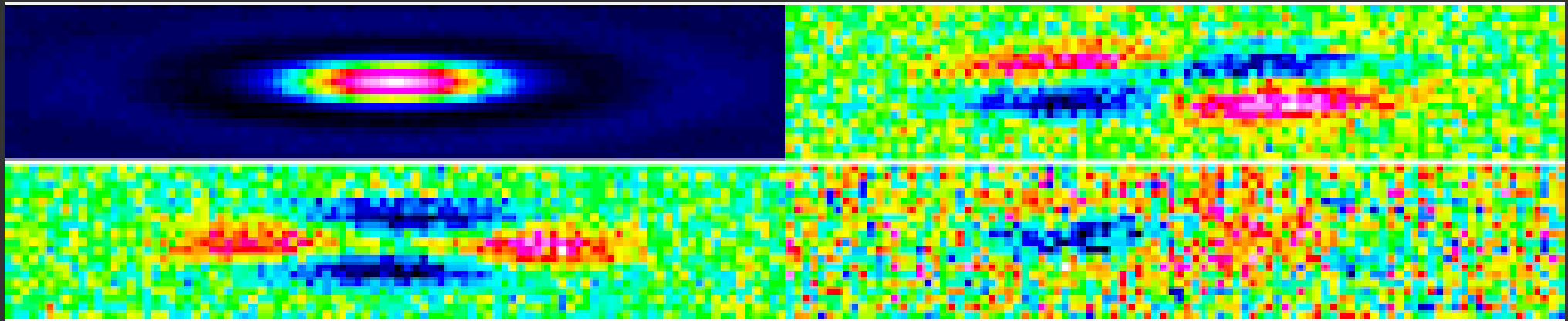
ALMA Full-Stokes Imaging

- ALMA Study Project to understand the issues with full-Stokes mosaic imaging (BK, PJ, UR, CH, PC (Chile))
 - Measured PB in Stokes-Q and -U did not show the Clover Leaf pattern! This is unphysical
 - Imaging tests (Stokes-V) remained inconclusive
- Characterize full-Stokes PB
 - Reprocess holography measurements at that time (early 2018)
 - Star/Radial scanning pattern
 - We could see the expected leakage patterns in all Stokes, but SNR was too poor
 - Radial pattern puts highest sensitivity at the center of the PB
 - Need high sensitivity in the **outer** parts of the PB
 - Under-sampled aperture
 - Position information was not recorded, added distortions



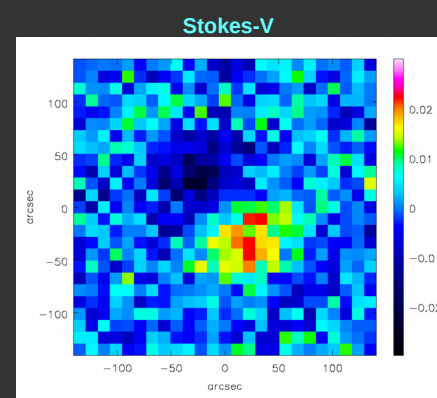
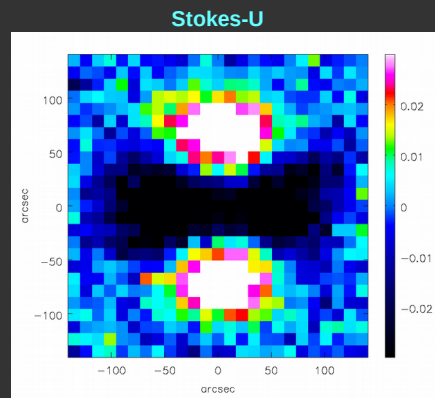
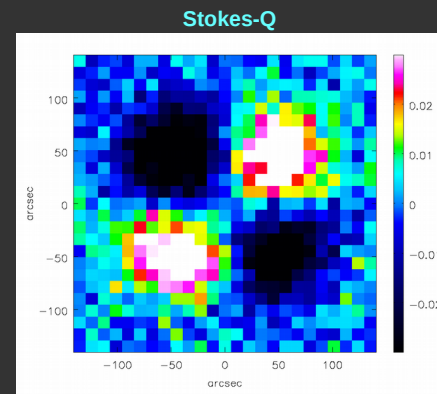
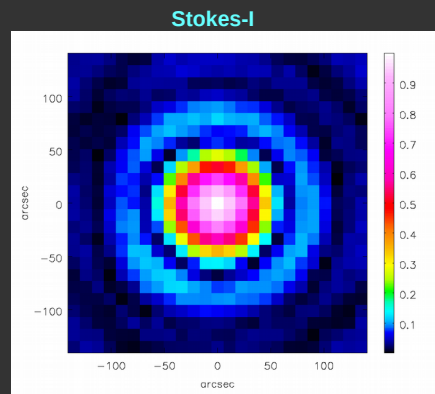
ALMA Full-Stokes Imaging

- New holography data acquired in Nov. 2018
 - Standard holography observing method
 - Standard CASA tools for data processing using standard ALMA calibration procedure
- Initial test observation with existing ALMA holography script produced “squashed” beams
 - Involved [PJ@NM](#) and [CH@Chile](#) debugging in real-time!



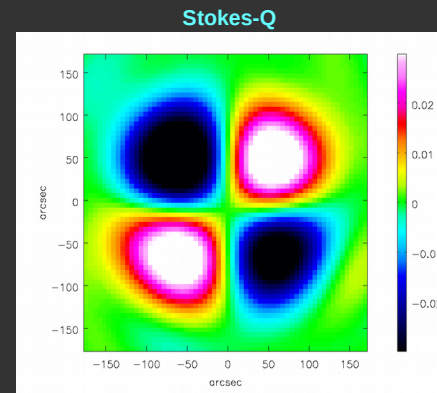
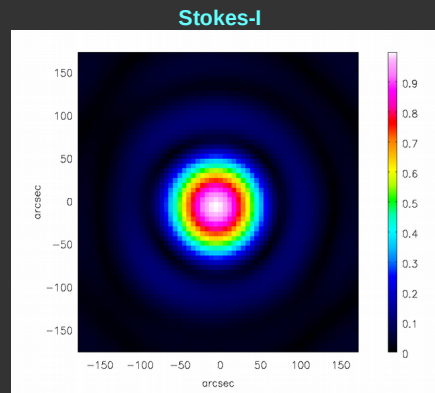
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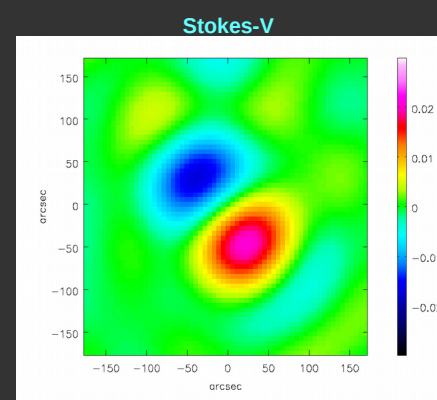
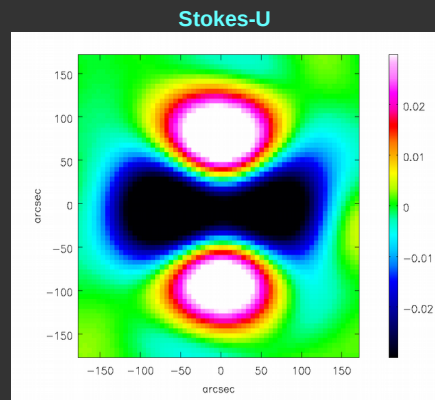


ALMA Full-Stokes Imaging

- Produced Zernike polynomial models using the holography data (shown below as PBs in Stokes-I, -Q, -U and -V)
- Work is in progress to integrated these models with A-Projection in CASA to enable full-pol mosaic imaging with ALMA



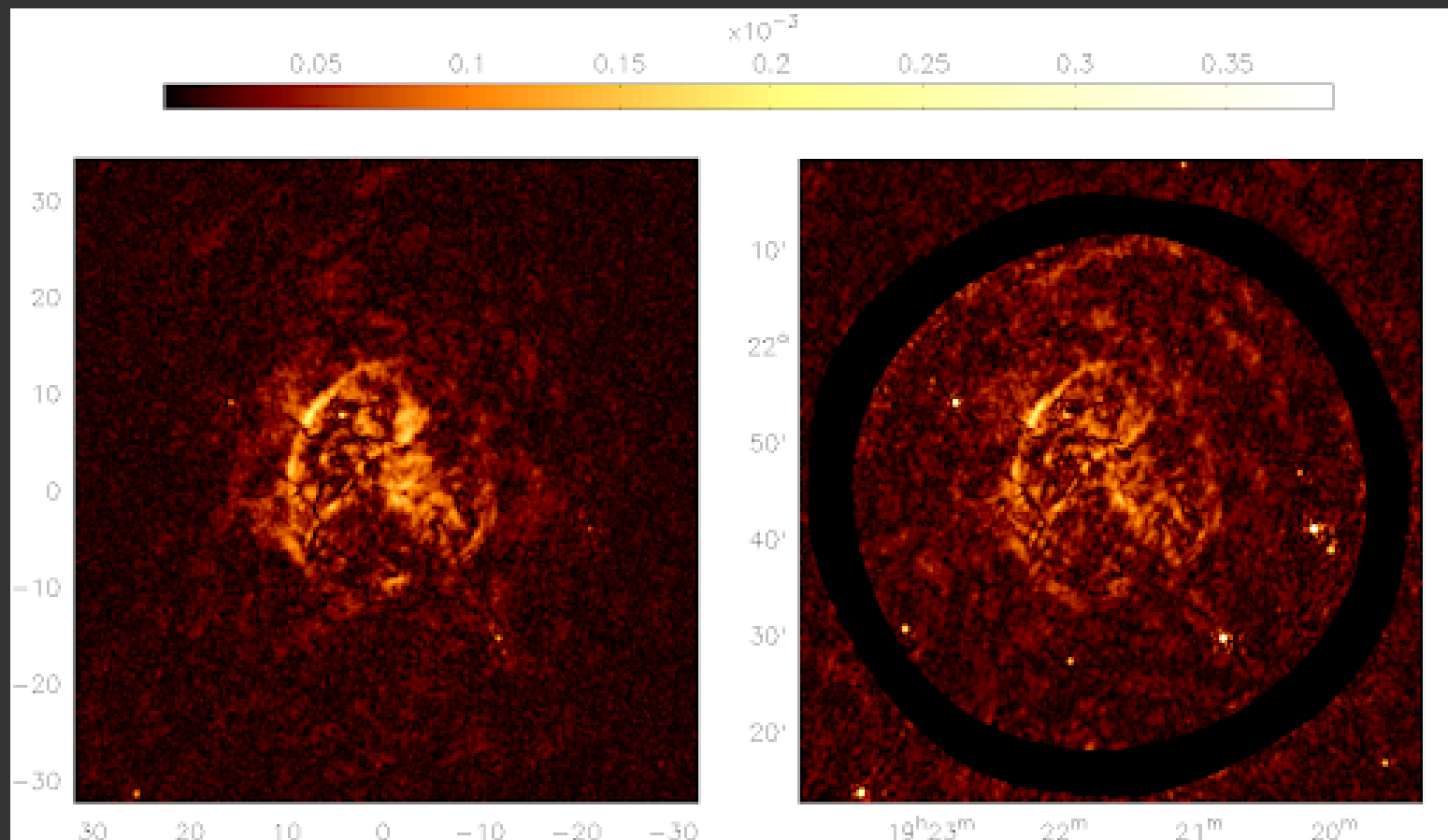
Stokes-Q, -U leakage
~3-5% in the main-lobe
Higher in the first side-lobe



Stokes-V leakage
~3-4% in the main-lobe
Higher in the first side-lobe

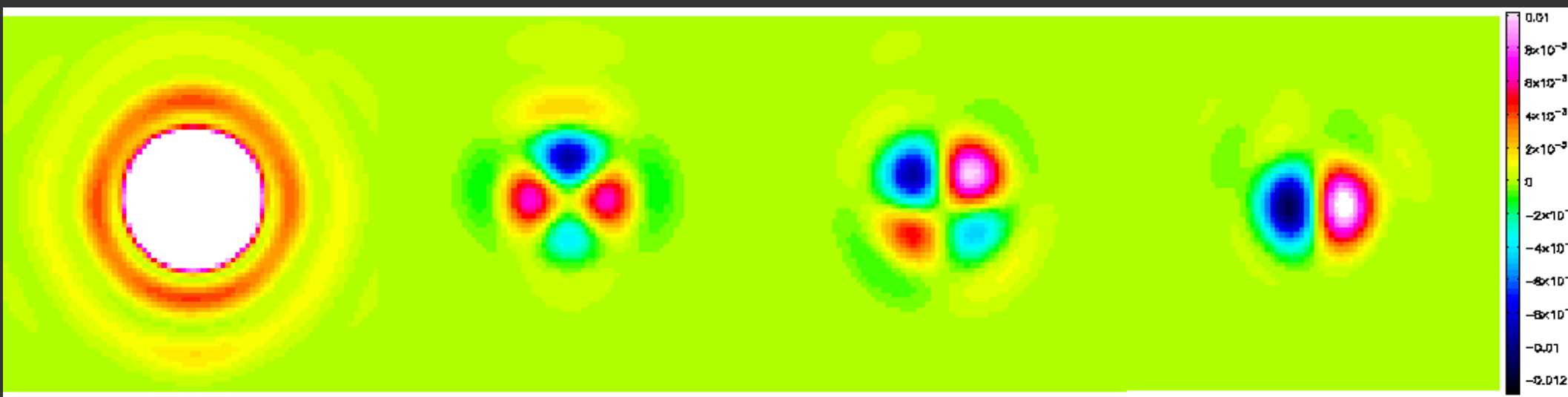
Full-Stokes Imaging

- Produce polynomial models for the A-term (shown below as $FT(A)$)
- Use these models in A-Projection to test mosaic imaging with ALMA



NRAO-IDIA, SA Collaboration (MeerKAT)

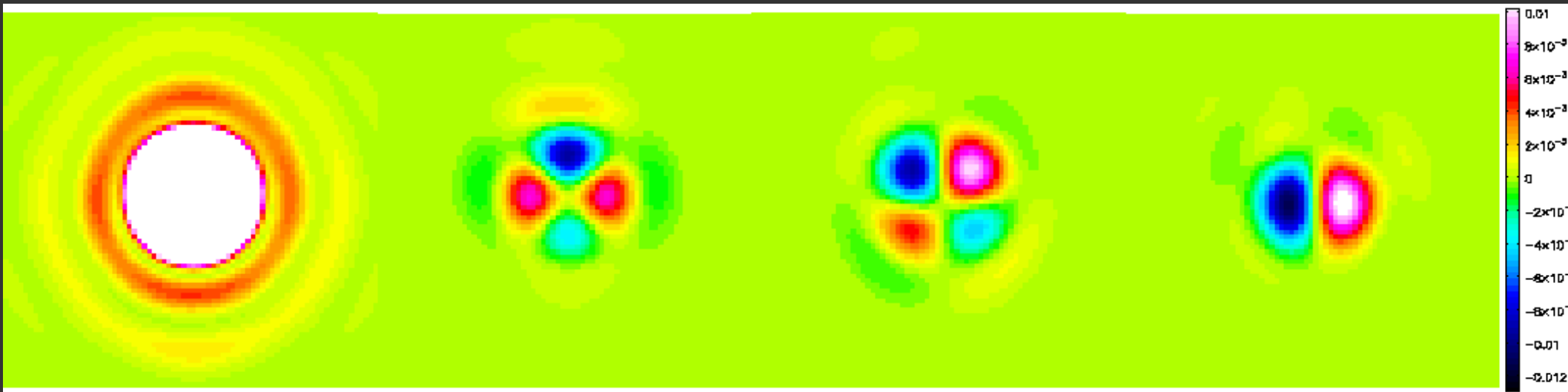
- The A-to-Z solver (Aperture-to-Zernike)
 - Holography (full-Stokes) → Antenna Jones matrix (the A-term)



- Easy to generate A-term for any telescope, given holography data

NRAO-IDIA, SA Collaboration (MeerKAT)

- Collaboration with NRAO-IDIA, SA
 - Holography (full-Stokes) → Antenna Jones matrix (the A-term)



Road Map 2020

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Plans are worthless, but planning is essential.

Dwight D. Eisenhower